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Erratum: "Cut-and-Permute Algorithm for Self-Avoiding Walks in the Presence of Surfaces" *J. Statist. Phys.* 108(1/2):252 (2002)

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The legend to Fig. 1 printed incorrectly. It should read as follows:

Fig. 1. Acceptance fraction for the different classes of pivot moves as a function of the rescaled variable $\alpha = k/N$, for $N = 100$. Three kinds of behaviour are visible at small values of α. At $\alpha = 0$ the acceptance fraction vanishes for 5 classes of moves transforming $z \to -z$, it is small for 6 classes corresponding to $\pi/2$ rotations and diagonal reflections in the (y, z) and (z, x) planes, while it is not affected by the presence of the surface for the remaining 4 classes of moves which do not modify the z coordinate. The correspondence between symbols and classes of lattice symmetries as defined in Section 2 is the following: 1.(a) z-axis inversion (□), 1.(b) x or y-axis inversion (∗), 2.(a) $\pm\pi/2$ rotation in yz [or zx] planes (■), 2.(b) $\pm\pi/2$ rotation in the xy plane (▽), 3.(a) π rotation in yz [or zx] planes (+), 3.(b) π rotation in the xy plane (×), 4.(a) diagonal reflection in the yz [or zx] planes (○), 4.(b) diagonal reflection in the xy plane (▲), 5.(a) diagonal reflection in the yz [or zx] plane and x [resp. y] axis refl. (●), 5.(b) diagonal reflection in the xy plane and z-axis inversion (▼), 6.(a) $\pm\pi/2$ rotation in the yz [or zx] planes and x [resp. y] axis refl.(△), 6.(b) $\pm\pi/2$ rotation in the xy plane and z-axis inversion (◇), 7. 3-axes reflection (♦), 8. diagonal reflection in the yz or zx planes and $\pm\pi/2$ rotation in the xy plane (⬠), 9. two diagonal reflections, one in the yz or in the zx plane and the other in the xy plane (⬟).

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